

Creating products and knowledge for the Mediterranean



ODYSSEA – REPORTING ON WP PROGRESS III. OBSERVATORIES

RV1 Review Meeting, 13 February 2019, REA, Brussels

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What is an Observatory?



- An Observatory is a facility providing observations (Wikipedia).
- Ocean observatories are platforms for studying the ocean and its fundamental processes in real time, while returning continuous streams of data and imagery back to shore-based researchers.
- They include suites of instruments and sensors, power supplies, computer command and storage capability, and Internet connections or other advanced communications systems. (Woods Hole).
- A few Ocean Observatories and observing systems are already in operation or under construction, while several larger ones are now being planned by universities and research institutions in conjunction with NSF's Ocean Observatories Initiative (OOI), the NOAA-led Integrated and sustained Ocean Observation System (IOOS), and other international programs.

What is an ODYSSEA Observatory?



They are pilot facilities referring to an **ODYSSEA local partner** with the aim to:

- Identify, contact and inform potential users and stakeholders needing marine data;
- Promote and train scientists and users on ODYSSEA Platform
- Customize the dashboard of ODYSSEA Platform according to users' needs
- Have trained staff to operate numerical models for local forecasts on sea conditions
- Have trained staff to operate and maintain at least a sensor at sea located at the facility of an end-user
- Have special interest to 'sale' services and products to marine and maritime users through ODYSSEA platform

The Observatories



- ✓ Integrate and Operate a network of 9 observing and forecasting systems covering coastal and shelf zone environments,
- ✓ Diverse systems from Ecologically-vulnerable systems (MPAs) to systems with increased human pressure,
- ✓ Combine monitoring and modeling activities,
- ✓ Produce new datasets with increased spatial and temporal resolution, stored, manipulated, made accessible through the ODYSSEA platform.



The Scope of ODYSSEA Observatories



The establishment and operation of ODYSSEA Observatories, will

- (a) Improve the spatial and temporal resolution of existing data;
- (b) Enhance existing knowledge along the North African and Middle Eastern coastline;
- (c) Develop, test and demonstrate novel monitoring systems for data collection;
- (d) Collect new marine parameters in line with EU policies;
- (e) Involve directly and train local/regional end-users in data collection and model results assessment; and
- (f) Provide operational modelling results to serve multiple end-users needs.

ODYSSEA Observatories ToR



Report 2.1 provides:

- the basic Terms of Reference for ODYSSEA Observatories operation;
- the geographical boundaries of each Observatory;
- establishes the spatial and temporal resolution and initial archived datasets and graphs retrieved from existing platforms;
- defines the procedures to map and contact end-users;
- analyses the infrastructure required;
- explains the operations requested; and
- determines the processes and models to be applied, the time needed for model runs and the flow of data from and towards the platform.

ODYSSEA Model Observatories ODYSSEA

Area	Country
Thracian Sea	Greece
Gulf of Gökova	Turkey
Valencia coastline	Spain
North Adriatic Sea	Italy
Arzew Bay/ Stora Gulf	Algeria
Gulf of Gabes	Tunisia
Al-Hoceima	Morocco
Israel coastline	Israel
Nile zone of influence	Egypt

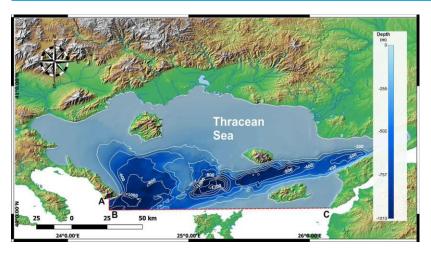
ODYSSEA Observatories factsheets

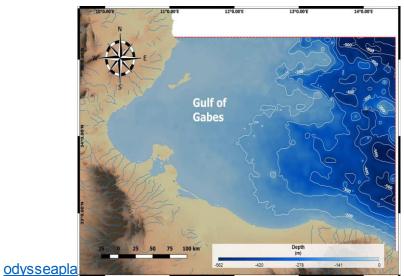


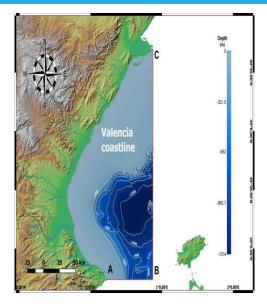
Observatory Name	National Park of Al-Hoceima (PNAH) Observatory
Country	Morocco
Geographic Area	The National Park of Al Hoceima is located on the Mediterranean Moroccan coast, 150 km east from the Gibraltar Strait, in proximity to the city of Al Hoceima and has a 47 km long coastline.
Oceanographic Interest	The area is affected by the surface Atlantic water jet-like flow through the Strait, moving eastward with strong currents and complex dynamics. Alboran basin topography induces anticyclonic gyres. Al-Hoceima is affected by the western Alboran Gyre (WAG) the combination of strong tidal currents at the entrance of the Strait, noticeable winds, mostly strong regional westerlies and easterlies regimes, and the existence of re-circulations at both margins of the jet.
Ecosystem Importance	The PNAH is an unusual biotope consists of caves, islets and rocks which host one of the most original biodiversity in the Mediterranean, like rare or threatened species from small invertebrates (giant limpet) to large marine mammals monk seal and dolphins. Also a very rich avifauna Osprey, Bonelli's Eagle, Audouins, and mixed fish abundance atlantics and Mediterranean Sea, and more than 500 types of algae.
Human Activity	The PNAH appears to be exposed to different human pressures that affect rare species survival and threaten local biodiversity. Direct effects of such threats, especially those resulting from illegal fishing practices such as dynamite fishing and poisoning, have strong implications for the entire marine biodiversity of PNAH.
Main Citations	[38-41]
End-User Groups	Port authority, fish farms, mussel farms, marine protected area management body.
Partner responsible	AGIR

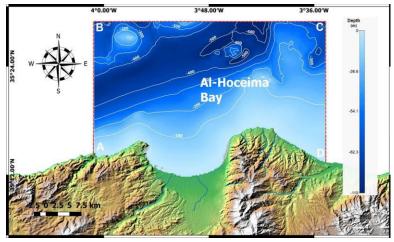
Spatial Boundaries of Observatories







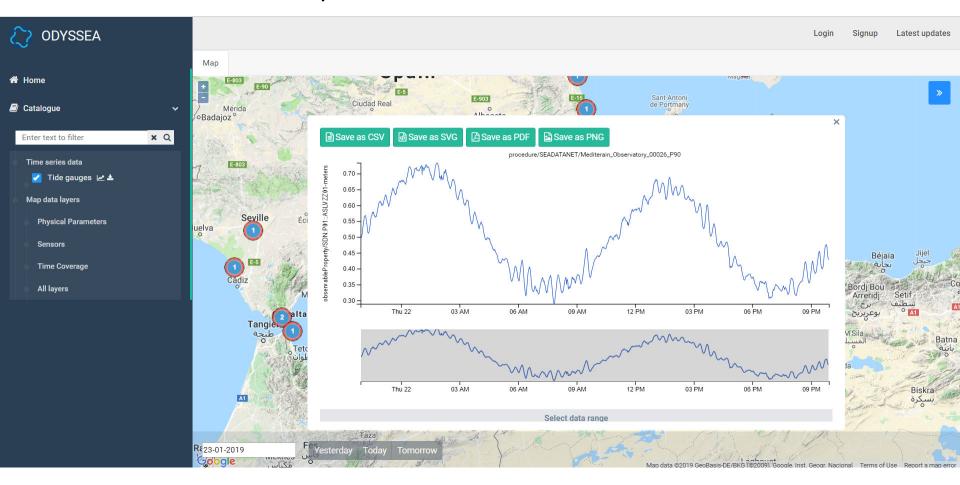




Use of ODYSSEA Platform in each Observatory



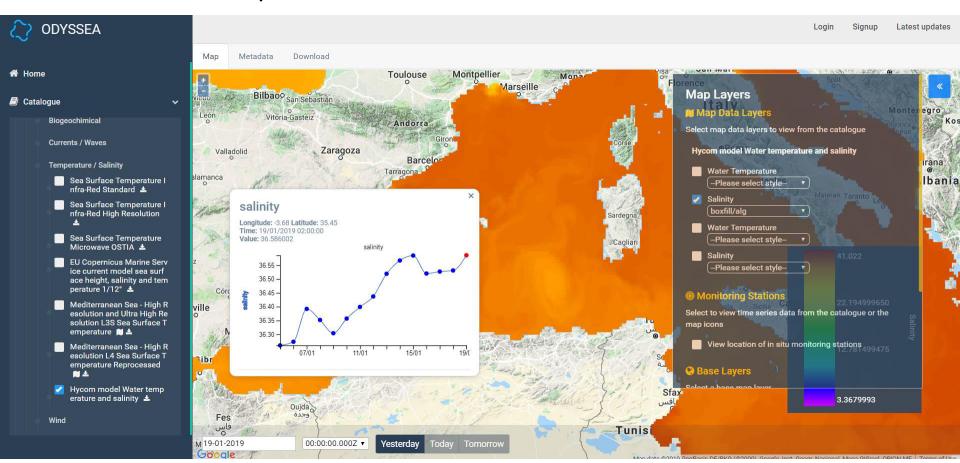
Tidal Sea Level Variability – Mediterranean Sea



Use of ODYSSEA Platform in each Observatory



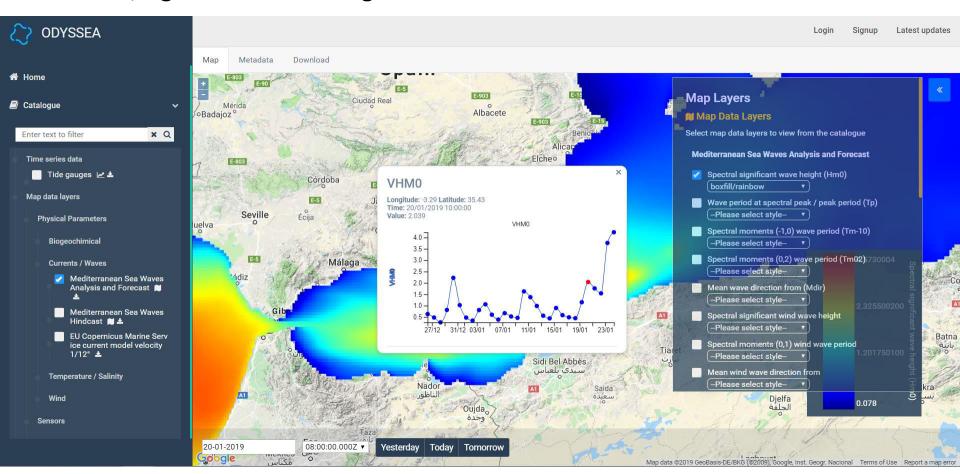
Sea Surface Salinity – Mediterranean Sea



ODYSSEA Platform



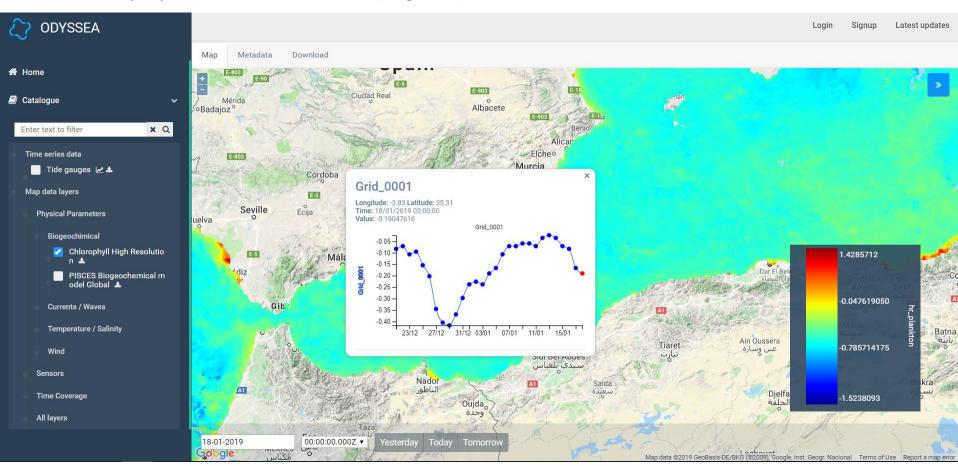
Waves, Significant Wave Height – Mediterranean Sea



ODYSSEA Platform



Chlorophyll-a, Concentration (mg/m³) – Mediterranean Sea



Collaboration with end-users





To: ODYSSEA Project

Democritus University of Thace

Xanthi, 67100 Greece

Attn: Mr. G. Sylaios

Marousi, 07 of September 2018

Subject: Collaboration with ODYSSEA

Dear Mr. Sylaios,

We accept your proposal for participating in ODYSSEA Project and collaborating in operating a station of real-time oceanographic data installed in our offshore installation of South Kavala.

The project will provide useful information to our marine operations and to multiple maritime sector end-users. Energean continuously supports the local community in multiple levels and recognizes that this project will provide valuable information to them.

Please proceed with drafting a detailed Collaboration Agreement.

For Energean Oil & Gas S.A.,

Dimitris Contikas

Managing Director





Collaboration with end-users



Turkey: Marine Protected Zone Organization

Israel: Offshore Fish farm

Egypt: Abu Quir Fishermen Association

Tunisia: National Hydrographic Service

Algeria: National Space Agency

Morocco: National Forestry and Water Agency

Valencia: Valencia Port Authority

North Adriatic: Italian Environmental Agency for

MSFD/WFD implementation

Static Monitoring Systems for ODYSSEA Observatories







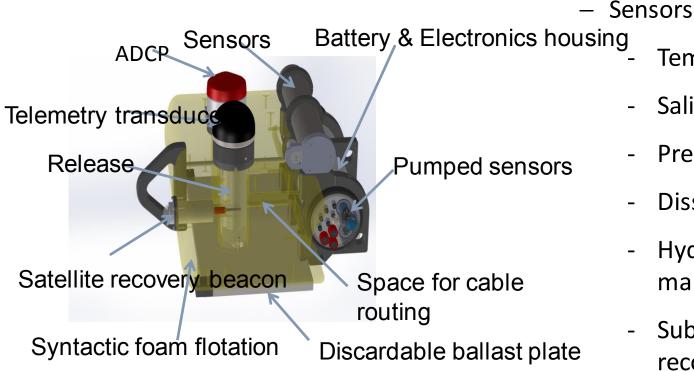




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Static Monitoring Systems for **ODYSSEA Observatories**





- Temperature
 - Salinity, pH
 - Pressure
 - Dissolved Oxygen
 - Hydrophone to record marine mammals
 - Submarine camera to record fish
 - Currents
 - Microplastics sensor

Mobile Monitoring Systems for ODYSSEA Observatories



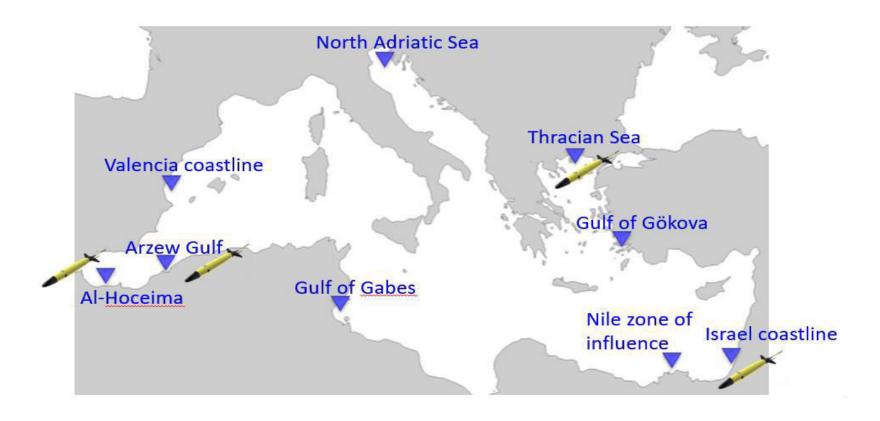
- 2 SEAEXPLORER GLIDERS
- 3 sensor payloads:
 - ❖ Payload 1
 - ✓ Temperature, salinity, pH, dissolved oxygen, chlorophyll-a, turbidity, CDOM
 - ❖ Payload 2
 - ✓ Passive Acoustic Monitoring (PAM)
 - ❖ Payload 3
 - ✓ Temperature, salinity, microplastics





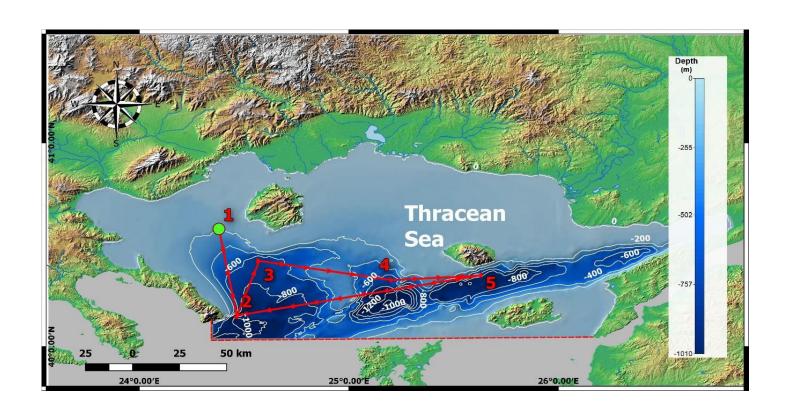
Mobile Monitoring Systems for ODYSSEA Observatories





Mobile Monitoring Systems for ODYSSEA Observatories



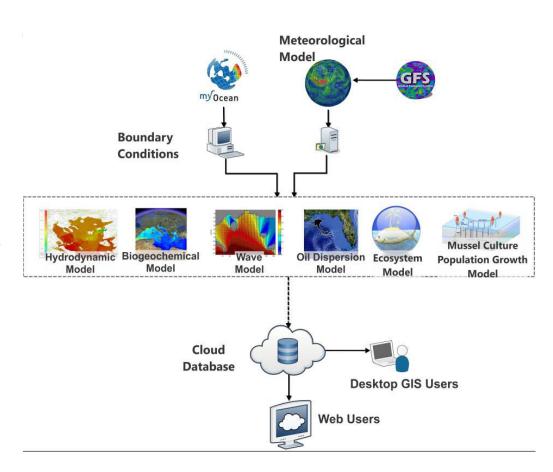


ODYSSEA

The Models

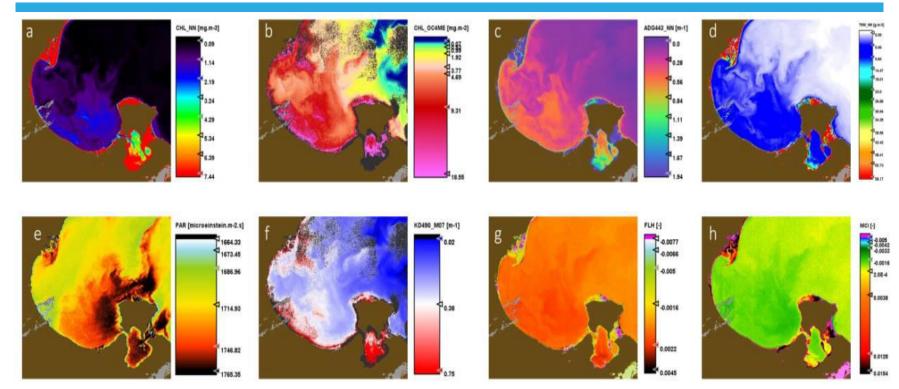
- A prototype 'chain' of operational models will be developed,
- Link models to existing databases,
- ✓ Provide short- and long-term prognostic results,
- ✓ Manage risks and emergencies in coastal and offshore areas,
- Meet the requirements of various end-user groups,
- Report on parameters never previously reported,

Models: Meteorological (WRF), 3Dhydrodynamic (Delft3D), Wave (SWAN), Oil spill (MEDSLICK-II), Water quality (DELWAQ), Ecosystem models (Ecopath with Ecosim), Fish and Mussel/oyster culture population growth



Remote Sensing





Sentinel-3 Level2 spatial distributions of a) chlorophyll-a conc (mg m⁻³) Oc4me algorithm, b) chlorophyll-a conc (mg m⁻³) chlnn neural network algorithm, c) absorption of CDOM at 443 nm (m⁻¹), d) TSM concentration (gm⁻³), e) PAR in the spectral range 400-700 nm (µEinstein m⁻² s⁻¹), f) diffuse attenuation coefficient at 490 nm (m⁻¹), g) fluorescence line height and h) max chlorophyll index at Gulf of Gabes.

Capacity Building





Networking, Training and Capacity Building in N. African countries

Organize workshops to train future managers and operators of ODYSSEA Observatories;

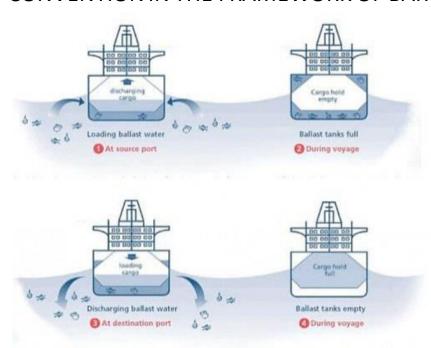
Organize personnel exchanges; Improve the professional skills and competences of those working and being trained to work in the blue economy.

Deviations from DoA



Valencia Observatory: IMPLEMENTATION OF THE BALLAST WATER CONVENTION IN THE FRAMEWORK OF BARCELONA CONVENTION





Pic Source: NOAA: International Maritime Organization

Deviations from DoA



Why Valenciaport

Valenciaport is a **leading Mediterranean port** in terms of commercial traffic, mostly containerised cargo, due to its dynamic area of influence and an extensive network connecting it to major world ports. Valenciaport is the best and most efficient option for maritime trade in southern Europe, with **connections to over 1000 ports throughout the world**

The Aim

The aim is to provide a tool for monitoring and implementing several EU and International policies as explained later, as well as, to conduct an harmonised implementation of the Ballast Water Convention in the Mediterranean basin. The data collected will provide relevant information to researchers and public authorities for assessing and controlling the impact of alien invasive species (AIS) in local ecosystems.

Deviations from DoA





WP2/9

- Analysis of data available and requested
- Cooperation and coordination between ports, environmental agencies and maritime administrations

ODYSSEA scope includes sampling of 3 sampling points located inside the port of Valencia.

Analysis of organisms in the water column:



- Phytoplankton.
- · Zooplankton.

Analysis of benthic organisms (from the bottom):

- Infauna (soft substrate organisms).
 - Epifauna (organisms that live on the bottom).
 - Fouling organisms.

Sampling frequency:

Quarterly for water.

• Annual for benthic organisms.

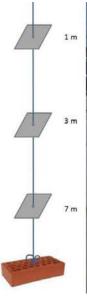
NOTE: Water quality data will be provided by the Port Authority of Valencia





TASK	MONTHS											
	M1	M2	М3	M4	M5	M6	M7	M8	M9	M10	M11	M12
Sampling of organisms in the water column												
Sampling of organisms in the water column and benthos												
Analysis of organisms in the water column												
Analysis of benthic organisms												
Partial report (water organisms only)												
Final report												







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The 9 ODYSSEA Observatories Operational Modelling



The scope of the modelling module of ODYSSEA observatories is to:

- (a) Provide short and long-term forecasts to serve multiple end-users needs;
- (b) Manage risks and emergencies in coastal and offshore areas
- (c) Improve the spatial and temporal resolution of existing data;

(d) Enhance existing knowledge along the North African and Middle Eastern

coastline;

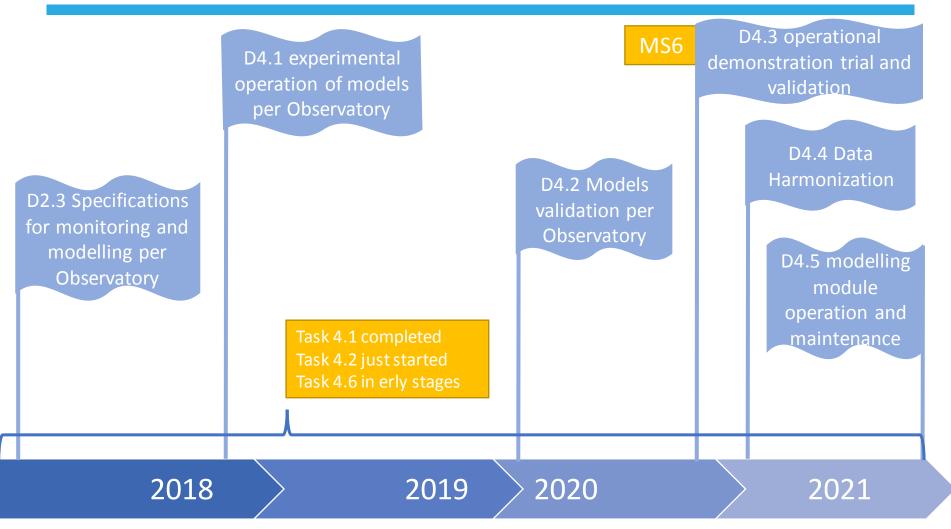
(e) Produce new datasets in line with EU policies;

(e) Train Observatory personnel in operating and maintaining the local platform.



Modelling Module Roadmap: Deliverables and milestones

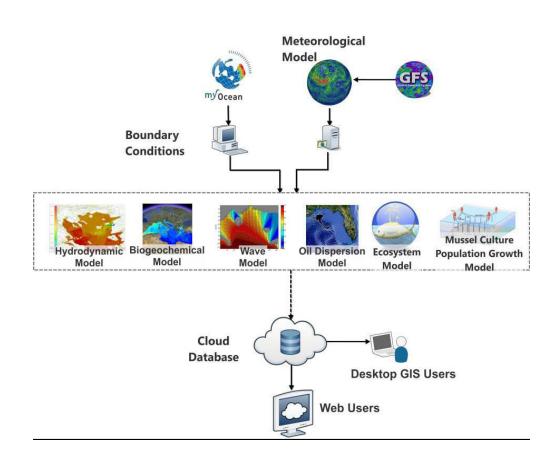




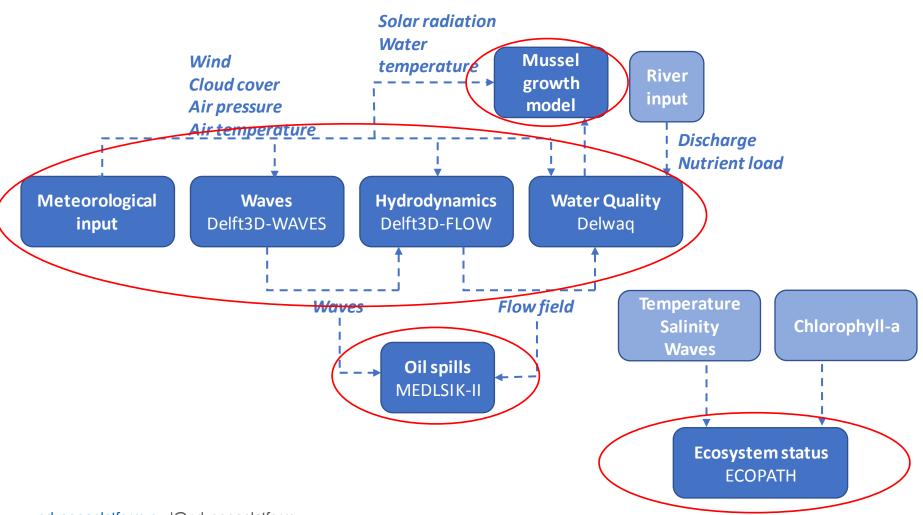


Objective: Set-up and experimental operation of models at Observatories

- ✓ models' coupling & interface
- ✓ establish iternal data flows
- ✓ Link to external databases and local sensors (for initial & boundary conditions, cal/val)
- ✓ Set-up a service chain
- ✓ Planned
 developments/modifications
 to models used for
 Observatories





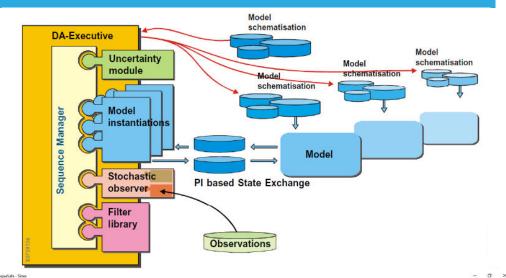




Available interface tools for models' operationalization:

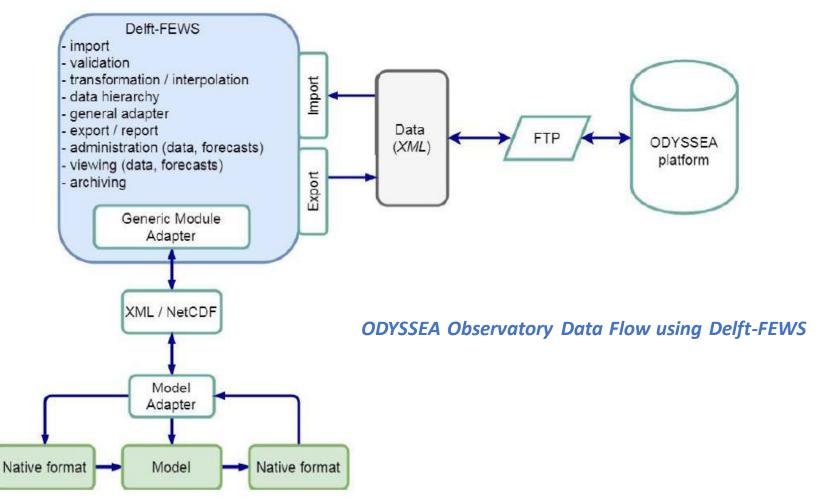
- ✓ Import of initial and boundary conditions
- ✓ Couple, sequence, run models in an automated manner
- ✓ Integrate data from local sensors and external databases
- ✓ Process and assimilate results
- ✓ Interface with ODYSSEA platform

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Training for Technical Staff and managers of ODYSSEA Observatories on Delft3D, Delft-FEWS and AQUASAFE



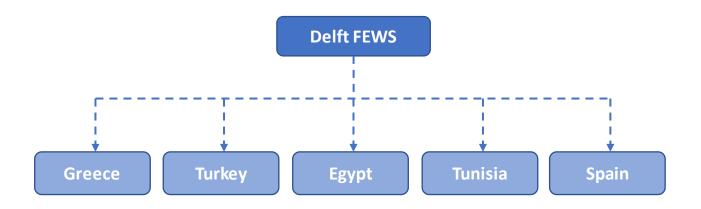
ODYSSEA workshop, 5-9 March 2018, Crete (FORTH)

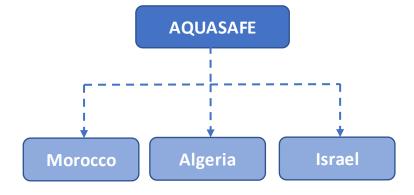


Comparative analysis of available interface tools (Delft-FEWS & AQUASAFE) for Thracian Sea based on a set of pre-established criteria

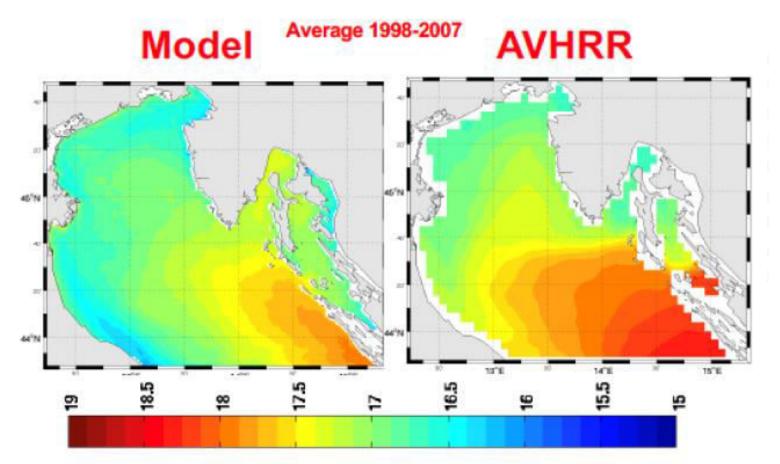
- General criteria: operationalization capacity, robustness, user-friendliness, computer capacity
 required computational time & effort, number of models the system can handle and their
 stepping and sequence, possibilities for expansion and flexibility (e.g. subsequent linking of
 additional models), ease to configure and adapt to users' needs.
- Pre-processing capacity: data import and links to external data sources, data assimilation options/capabilities, ease of link to new sensors.
- Post-processing capacity: visualization options, data analysis, reporting, setting up automatic
 alarms and warnings.
- Publication capacity: availability of web-publishing services.









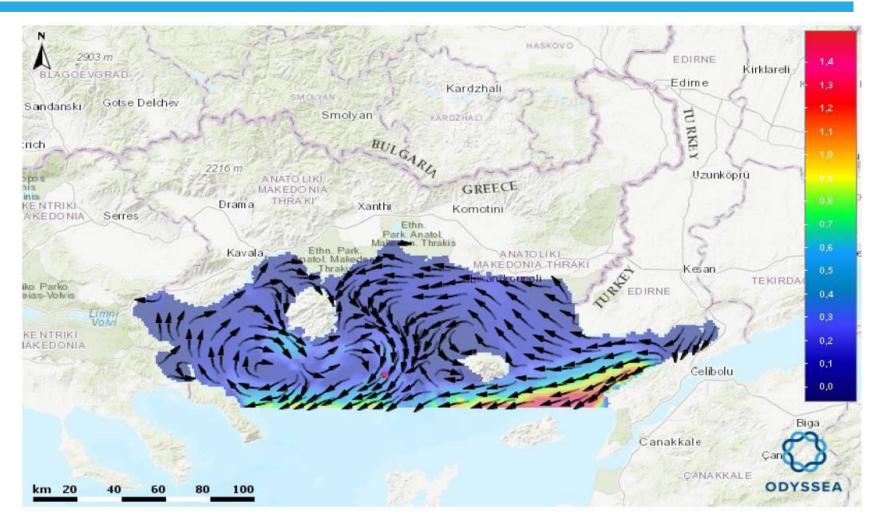


AVERAGED SEA SURFACE TEMPERATURE DISTRIBUTION DURING 1998-2007



Data Information									
Provider	National Centres for Environmental Prediction (NCEP)								
Product identifier	gfs.tCCz.pgrb2.0p50.fFFF, gfs.tCCz.pgrb2.0p25.fFFF								
Downloaded Variables	wind velocity X (ms ⁻¹), wind velocity Y (ms ⁻¹), atmospheric pressure (Pa), solar radiation (Wm ⁻²), air temperature (°C), relative humidity (%), precipitation (mm), wind modulus (ms ⁻¹), wind direction (°), wind gust (ms ⁻¹), cloud cover, downward long wave radiation (Wm ⁻²)								
Geographical coverage	-180.0 180.0								
Areas	Global-ocean								
Spatial resolution	0.25 degree								
Vertical coverage	Values at 10 meters high								
Temporal resolution	Hourly								
Temporal coverage	Table 10 Part of the Company of the								
Update frequency	Four times a day								

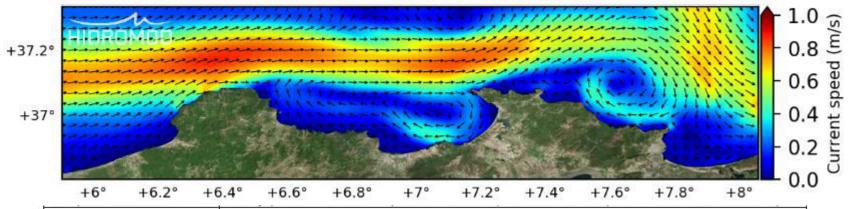






	Data Information
Model identifier	Algeria_Model
Domain Name	Algeria

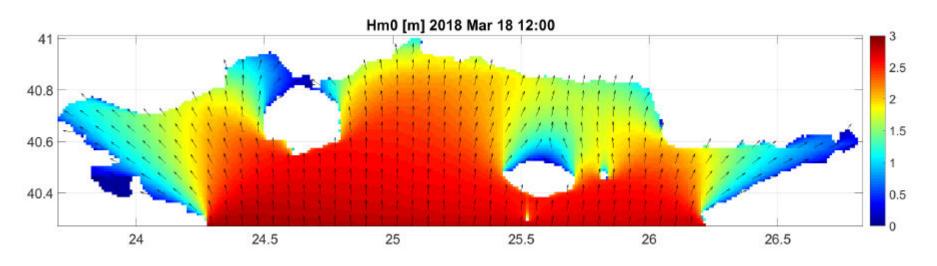
HIDROMOD MOD 3D - 0.8 km Nov. 05, 2018 00:00 UTC+0000



Temporal coverage	Under configuration
Local Stations	Collo, Skida Port and Stora
Vertical coverage	From -2855 to 0 m
Hindcast	1 day
Forecast	2 days

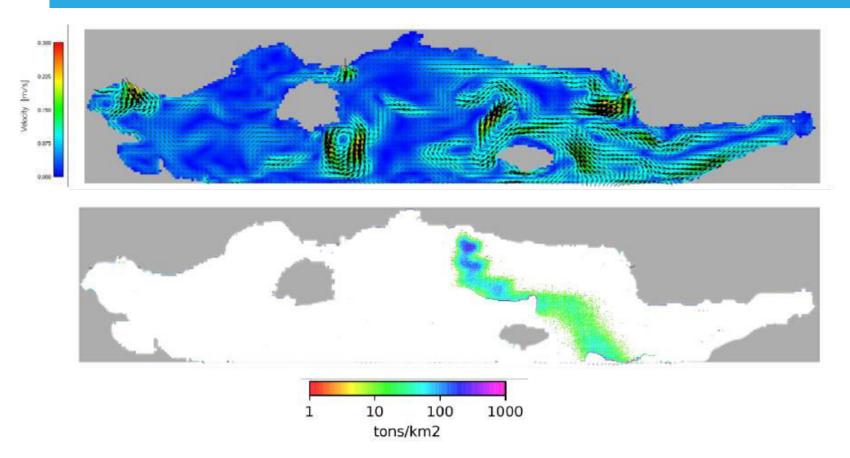


Pilot runs of SWAN model (Delft-WAVES)



Indicative model outputs for significant wave height from SWAN for Thracian Sea





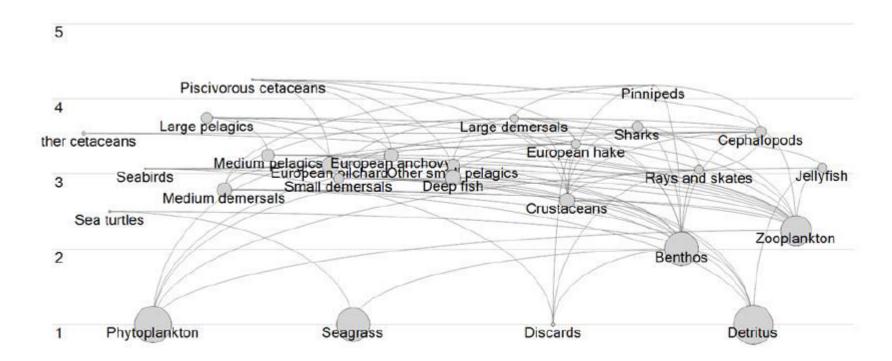
Indicative output maps of surface currents and surface slick concentration from MEDSLIK-II for Thracian Sea after 5 days of simulation



Pilot runs of ECOPATH model







FLOW DIAGRAM OF THE FIRST TEST MODEL FOR THE MEDITERRANEAN MOROCCO OBSERVATORY, ORGANISED BY THE TROPHIC LEVELS OF 26 FUNCTIONAL GROUPS

impacted group																												
1: Piscivorous cetaceans	2: Other cetaceans	3: Pinnipeds	4: Seabirds	5: Sea turtles	6: Large pelagics	7: Medium pelagics	8: European pilchard	9: European anchovy	10: Other small pelagics	11: Large demersals	12: European hake	13: Medium demersals	14: Small demersals	15: Deep fish	16: Sharks	17: Rays and skates	18: Cephalopods	19: Crustaceans	20: Jellyfish	21: Benthos	22: Zooplankton	23: Phytoplankton	24: Seagrass	25: Discards	26: Detritus	1: Fleet1	○ Positive ● Negative	
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۰			٠		۵	•	•	٠	•	•	4																9: European anchovy	
					,	•	•		٠	4	4	,	,													•	10: Other small pelagics	
		•					•		٠	•	•	٠	•	٠	,	٠	٠										11: Large demersals	
•			•				4	•	٠	•	٠	,	,					•								•	12: European hake	
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MIXED TROPHIC IMPACTANALYSIS OF THE FIRST TEST MODEL FOR THE MOROCCO O BSERVATORY

Impacting group



Deliverable 4.1: Experimental operation of models per Observatory submitted on time



Operating a network of integrated observatory systems in the Mediterranean Sea

Project Deliverable Report

Deliverable Number: 4.1

Work Package Number: 4

Deliverable Title: Experimental operation of models per Observatory
Author(s): Georgios Sylaios, Adelio Silva, Nikolaos Kokkos, Konstantinos
Zachopoulos, Katerina Spanoudaki, Menno de Ridder, Caroline Gautier, Lorinc
Meszaros, Marco Zavatarelli, Athanasios Tsikliras, George Tserpes

This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 727277

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Difficulties, delays and corrective actions



- ✓ Some delays were experienced as Delft-FEWS was a tool not previously applied as an interface to downscale CMEMS modeling products, and thus significant effort was required in terms of algorithmic development, to make the system compatible and capable to read and download the CMEMS NETCDF files at daily basis
- ✓ Significant efforts required to gather local data (biomass, catches) from Observatories where ECOPATH with ECOSIM will be implemented (Morocco, Egypt, Turkey)
- ✓ Corrective actions: Increase efforts to complete the modeling chain at all Observatories
 → SWAN is already implemented through FEWS for Thracian Sea and can be duplicated for remaining Observatories

Next steps



- Workshop on SWAN and DELWAQ
- Tasks 4.2 & 4.3: Models testing and calibration in each Observatory,
 Models validation in each Observatory
- Implementation began during the last month of RP1
 - Testing, calibration & validation activities for models at each Observatory
 - Ad-hoc metrics defined, data analysis and visualization options facilitated by Delft-FEWS & AQUASAFE platforms
 - Performance of models evaluated in hindcast mode (calibration) using available historical data both satellite and in-situ
 - Example data sets from CMEMS: SST_MED_SST_L4_NRT_OBSERVATIONS_010_004, INSITU_MED_NRT_OBSERVATIONS_013_035, SEALEVEL_MED_PHY_L4_NRT_OBSERVATIONS_008_050
 - Metrics passed to Task 4.3 for validations tests (forecasts experiments)
 - D4.2 on month 36 (RP2), including activities of Tasks 4.2 & 4.3

Observatories – regarding equipment

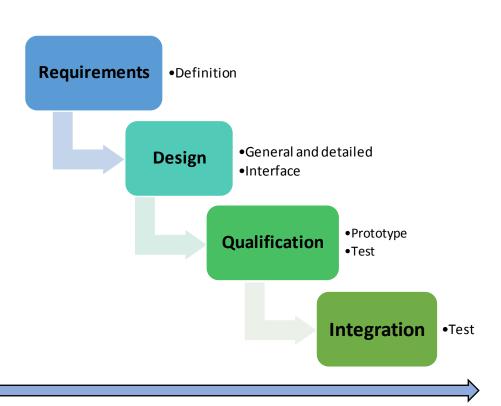


- Progress made in RP1
- Main results obtained: focus made on the µPlastic and the PAM
- Deliverables and milestones achieved
- Problems occurred and solutions
- DEVIATIONS from the DoA
- Next steps planned

Observatories – regarding equipment

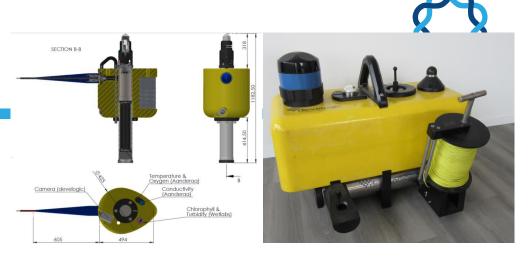


- New equipment were created or adapted and built for ODYSSEA (sensors, gliders, suface platform, landers)
- During the WP5 monthly meetings, we exchanged technical information in order to bring inovatives solutions to odyssea equipment



Equipement built

Landers and surface platforms from Develogic:



Surface platforms

Landers

SeaExplorer Gliders from Alseamar:

- 2 vehicle
- 3 different payload:
 - FLBBCD + CTD DO
 - μPlastic (from Leitat) + CDT DO
 - Acoustic

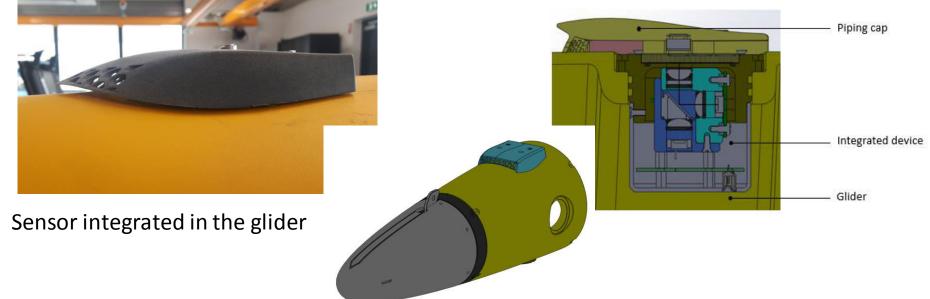


Glider

Focus on the µPlastic sensor: for gliders

Functional principle:

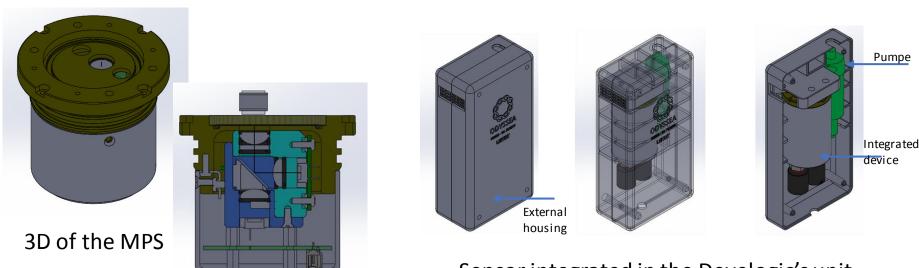
- The proposed strategy for underwater in-situ microplastic monitoring is to gather and detect the fluorescence light which is emitted by such contaminant particles when they are excited with a UV light source.
- This must be done in real time at the speed of which the microplastics circulate through the seawater pipe that brings the particles to the sensor's sampling point and without the ability to immobilise the particle at any time.
- The Microplastic sensor is integrate in the top of the payload of the glider:



ODYSSEA

Focus on the µPlastic sensor: for other platforms

- The Microplastic sensor was fully redesign during the 1st RP of ODYSSEA in order to be integrable on gliders, surface platform and landers. This resulted in 2 different designs.
- The sensors are currently being integrated on platforms.
- The same device is used for the glider, the lander and the surface platform. The dimensions has been based on the glider's puck because it is the most restrictive one.



Sensor integrated in the Develogic's unit

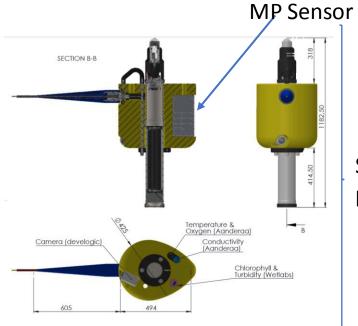
ODYSSEA

• The Microplastic sensor and the pump, for the Lander and the surface platform, are integrated in an external housing

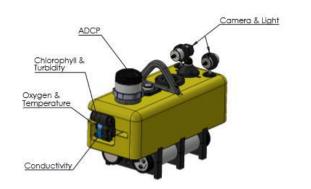
Focus on the Landers and surface platform

Landers and surface platform:

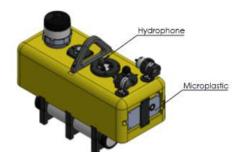
- The design has been finished: the μP sensor has been implemented in the drawings, and connection to the electronics should not be of any concern.
- All system should be ready for training in May, and shipment in June



Surface platform



Landers drawings



Focus on the µPlastic sensor

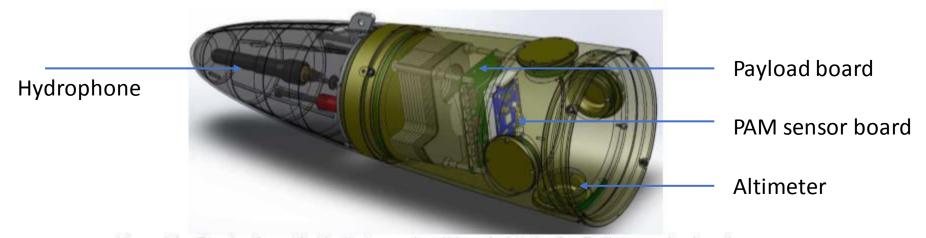
There are currently two different versions:

- MPS, to be implemented on Glider (ALSEAMAR platform)
- MPS-WP, to be implemented on Lander and Sea Surface (DEVELOGIC platforms).
- The only difference between those two versions is the way the sensor obtains physical particles from the environment: on the MPS version, the sensor uses the movement momentum of the glider to obtain particles, while the MPS-WP version uses a water pump.
- The rest of the electronic components, the detection algorithms, communications, and mode of operation are exactly the same for both versions.
- This approach facilitate the development of the sensor since there is only one generic design to develop that can be tuned up (using additional components such as a water pump or an external housing) to enable the implementation of the sensor in all platforms).
- Also, since both versions runs using same firmware (with the same theory of operation) all data reported from all MPS can be correlated to obtain higher level information.

Focus on the Passive Acoustic Monitoring system



- Single channel broadband acoustic recorder, signal processor and digital hydrophone.
- The vehicle section will host the Passive Acoustic Monitoring (PAM) sensor and contains the payload electronics (independent open-source CPU) and the altimeter



View of the Passive Acoustic Monitoring system integrated in the SeaExplorer payload section

 Acoustic data will be collected at the end of the glider navigation and is synchronized to the internal SeaExplorer clock, allowing to easily overlay this data with the glider navigation behaviour.

Focus on the Passive Acoustic monitoring system



Technical informations:

POWER	Internal Power: 12 x AAA Cells (user replaceable)							
	External Power: 4.5 - 30 V DC, Standard "Snap On" Packs Available							
ACOUSTIC	Analogue Bandwidth > 150 kHz, less than Sea State 0							
	ADC: 24 Bits Sigma Delta							
	Dynamic Range: 110 dB (full bandwidth)							
	Configurable Gain: 0 dB- 40 dB							
	Maximum Sensitivity: -165 dB Re 1 $\mbox{V/}\mu\mbox{Pa}$ to 205 dB Re re 1 $\mbox{V/}\mu\mbox{Pa}$ With Gain Control							
	Sampling Rates Supported: 24 kHz, 48 kHz, 96 kHz, 192 kHz, 384 khz (option for 500 kHz)							
	Programmable High Pass Filter: Software Controlled							
MEMORY	Up to 2 TB, Internal Removable SD Card Storage							
	Configurable recording, schedule and duty cycling							
DIMENSIONS	70mm x 233mm, 4.5lbs							
SIGNAL PROCESSING	Real Time One Third Octave Spectral Processing							
	RMS SPL Computed In All One Third Octave Bands from either 10 Hz -10 kHz or 20 Hz - 20 kHz, or 40 Hz - 40 kHz							

COMMUNICATIONS	Real Time Ethernet Streaming - spectrograms, live audio, configuration and data download
	Bluetooth for setup and configuration with Android Phone or Tablet
ENVIRONMENTAL	2000m depth rated (deeper on request)
	Operating Temperature: -10°C to +-50°C
INTEGRATED SENSORS	3 Axis Accelerometer, Gyro, Compass
	"Specifications subject to change without notice. Pressure to 200 bar (Accuracy 0.15% FS), Water Temperature (+/- 2°C)
	Real Time Clock
EXTERNAL INTEGRATION	GPS Input for PPS Time Synchronization
	Real Time Buoy

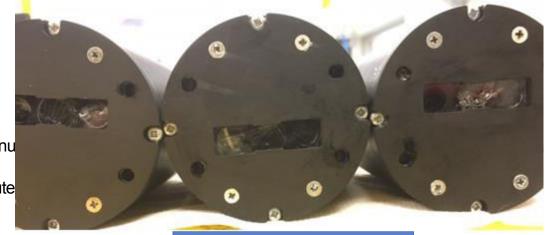
Problem occured and solution ODYSSEA

Before sending a prototype to ALSEAMAR and DEVELOGIC and making the mechanical integration on the different systems, some test have been realize like the communication or the pressure:

- In order to verify the communications between the MPS and the CCU of the different platforms, an evaluation board have been send to each partner.
- The evaluation board will behave like the MPS, reporting (fake) data like the MPS would do, allowing to be configured with the same commands as the MPS, switching ON/OFF with the reset button and detecting a MP if the user button of the evaluation board is pressed.

• To validate the robustness of the sensor and to qualify the 1000m rated in pressure, Leitat had to follow the pressure tests procedure bellow:

- 0 to 120bars at 12bars/min
- Stage at 120bars during 8h
- 120 to 0bar at 12 bars/min
- Stage at 0 bar during 15 minutes
- 500 x cycles at 110bars with :
 - 0 to 110bars at 12bars/min
 - Stage at 110bars during 1 minu
 - 110 to 0bar at 12 bars/min
 - Stage at 0 bars during 1 minute



Problem occured and solutions

- The development of a new sensor is very complex.
- This sensor was supposed to dive to 1000 meters but the windows cracked, the glasses crashed after 8h at 120 bars.
- The window material has been changed: first material quartz, replaced by sapphire), the sapphire puck has not been tested yet in the pressure test, test will be done during this month (february 2019)
- The window material is currently changed and new tests are ongoing with a test software at Alseamar and Devologic permises provided by Leitat, in order to pursue the electrical / software integration of the sensor.



Deviation from DOA



- The training and first missions will occurs beginning of April which is 5 months later than in the DOA:
 - Difficulties to create and install new sensors on platform (example of windows cracked during pressure test reagrding the micro plastic sensor)
 - However it would have been difficult to start all the deployments of instruments in winter time, due to poor weather conditions and / or holidays

Next steps planned



• Training is planned for the 8th to 12th of April 2019 at ALSEAMAR (which means that all equipment described previsously will be operational)

Objectives

- Learn how a SeaExplorer glider works in order to be able to prepare and operate the glider for scientific missions.
- Know-how :
 - Equipment functioning
 - Equipment preparation
 - Mission preparation
 - Deployment / Piloting / Recovery
 - Maintenance

Program

Day 1: SeaExplorer Overview

- Presentation, round table
- Glider Principle and system breakdown
- Vehicle description
- Payload description
- Review of the day, Questions & Answers session (Q&A)

Day 2: Getting the instrument ready

- Ballasting
- Magnetic compass calibration
- · Presentation of the day: piloting
- · Review of the day, Q&A session
- Programming of the upcoming mission with the different observatory manager

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Day 3: Mission Preparation

- Mission's files preparation
- Glider simulation
- Getting ready to go at sea
- Review of the day, Q&A session

Day 4: At-sea Operations

- Safety at sea
- Deployment
- Field exercises
- Recovery
- Review of the day, Q&A session

Day 5 : Piloting & Maintenance

- Piloting
- Working on the dataset
- Maintenance
- Additional operations
- Review of the day, Q&A session

Deliverable and miles stones achieved



D5.1 delivered on time

« Technical report sensor development and integration »



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Creating products and knowledge for the Mediterranean



THANK-YOU

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This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 727277